Interactive comment on “Plume-SPH 1.0: A three-dimensional, dusty-gas volcanic plume model based on smoothed particle hydrodynamics” by Zhixuan Cao et al.

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Authors’ reply to the comments by Anonymous Referee (Referee #2) of the manuscript gmd-2017-119

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by Zhixuan Cao et al.

The comments by the reviewer are recited in italics, followed by our reply in upright font. Equation, section, and figure numbers in our response are corresponding to these in the original version of GMD discussion paper.

General Comments

After reading the paper, I think the proposed method is highly detailed and the type of discretization properly described.

We would like to thank the reviewer for carefully reading our work and giving constructive comments. We have revised the manuscript as shown in the supplemental PDF file, and we hope that we have dealt with all suggestions in an adequate manner. The revised manuscript is also attached.

On behalf of all co-authors.
The following are our responses to reviewer’s specific comments. Modifications are made accordingly in the revised manuscript.

**Specific comments**

1. **Please add the recent papers, which I consider, are related to your research:**


Thanks for pointing out some of the more recent work on volcanic plume modeling. Work by Costa et al. (2018) motivates the development of more comprehensive 3D computational models like those in this paper. Reading this paper has inspired new application ideas for Plume-SPH. Citation of this paper is added in "Introduction" section to emphasize the advantage of developing more comprehensive plume model based on SPH.

We have considered coupling a volcanic plume model with a magma reservoir model. It is critical for any plume simulation to use more accurate eruption conditions, which might be obtained from a magma reservoir model. Thank you for pointing out the new degassing model to infer magma dynamics in volcanic plumes Terray et al. (2018). Comments regarding coupling volcanic plume model with magma reservoir model are added in conclusion section of this paper along with proper citation.

*It would be nice to provide a theoretical bound for the computational effort of your method for a single simulation step and the numerical-grid resolution. You can make*
use of, for instance, the number of long-computations (e.g., matrix-vector products). Then, please provide a theoretical bound for such value when computations are performed across different processors.

Our interpretation of the reviewer’s request for “theoretical bound for computational effort” is the operational complexity of the algorithms used. Apologize if we have misunderstood.

Without accounting for the detailed algorithm, the complexity for raw SPH method is $O(N \times N)$ operations. Where, $N$ is the total number of particles (SPH particles are essentially equivalent to discretization points in mesh-based methods). By adopting a background mesh and a compact-supported kernel function, the complexity will be reduced to $O(MN + mN)$. Where $m$ is the average of number of particles within the compact support of the kernel function, $M$ is number of particles among which neighbor searches are carried out. Please note that number of particles within the compact support of the kernel function is not constant in our case.

When computations are performed across different processors, theoretically speaking, the total computational time will be $(s + \frac{p}{n} + \bar{p})$, where $(s + p)$ (time needed for $O(MN + mN)$ operations) is total sequential computational time with $p$ representing computation that is parallelizable and $s$ represents computation that can not be parallelized, $n$ is total number of processors and $\bar{p}$ is extra computation and communication introduced by parallelization, for example, unnecessary duplication of work, communication overhead, time to split and combine.

It requires complete analysis of the detailed algorithms and instrumented data gathering to obtain more accurate theoretical and achieved bounds. We agree that such time complexity analysis would be very helpful for future performance optimization. However, considering HPC is not the major focus of this paper, we would like to reserve this topic for future research. We thank the reviewer again for proposing this idea.
It is not clear for me how the parallelization is performed, for instance, for a given time, do you split the domain across different processors? in such case, what constraints must be satisfied at each local domain in order to guarantee a consistent numerical solution of your equations?. Other possibility is to speed-up matrix computations, is this your case? or both?

The parallelization is not covered with enough details in this paper as it has been addressed in a separate paper Cao et al. (2017). The parallelization is achieved only by splitting the computational domain (Fig. 2(c) in GMD discussion paper shows a typical domain decomposition). No matrix computation is involved in the SPH scheme, so there is no parallelization regarding solving the matrix in our case. For any subdomain, information from its neighboring subdomains is required when updating physical quantities. To guarantee consistency, data is synchronized after each updates of physical quantities in the shared (or "halo") regions.

To address your questions and clean up confusion, we made a major revision in section 3.10 (is section 3.9 in the revised manuscript). In addition, portion of our response to reviewer’s second comments are also added in section 3.10.

We thank reviewer again for the careful reading and constructive comments.

**Major adjustments of the manuscripts**

Here is a summary on major adjustments made in the revised manuscript: Major revision is made in "Parallelism and performance" section (section 3.10 in original manuscript and 3.9 in the revised manuscript).
References

